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September 27, 2006 1.

Derivation 2-4:

Geodesics on a

spherical surface

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Points on a sphere of radius  $R$  are determined by two angular coordinates, an azimuthal angle  $\psi$  and a polar angle  $\theta$ :  $\hat{r} = R(\sin \psi \cos \theta \hat{i} + \sin \psi \sin \theta \hat{j} + \cos \psi \hat{k})$   $\hat{r} = x \hat{i} + y \hat{j} + z \hat{k}$  When moving on the sphere, the ...

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(check it!!) Grader:  
Muxin Han. He will  
have office hours (to  
answer questions  
about grading) in  
Nicholson 265, Fridays  
1-2pm (or "ping-pong  
room 5pm-6pm almost  
every day") Fall'05  
midterm, final exam.  
Grades: Midterm  
Grades, Homework  
Grades (posted Dec 8).  
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The solution of the equation is of the form:  
 $u(\theta) = r^{-1}(\theta) = A \cos(\omega\theta) + \frac{mk}{l^2\omega^2}$ , (4)  
where we have chosen the arbitrary phase  $\delta = 0$ . Depending on the value of the energy the orbit is either an ellipse, or a parabola or an hyperbola.

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on "Classical

Mechanics" by Herbert  
Goldstein, Charles P.

Poole, Jr., John L. Safko,  
3rd Chapter 2.

Lagrange's equations

Problem A. edition (10  
points) Consider a

mass  $m$  that hangs

from a string, the other  
end of which is wound  
several times around a

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Chapter 3, problem 13,  
19a, 20a; Marion and

Thronton, 5th Edition,  
Chapter 8, problem 34  
(see also Example 7-4  
in M&T, 5th) A particle

of mass  $m$  is  
constrained to move on  
the inside surface of a  
smooth cone of half-  
angle  $\alpha$  (see  
picture below). The

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particle is subject to a gravitational force.

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